Interrupt
Chapter 10

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Contents

- Polling Vs. interrupt
- Interrupt unit
- Steps in executing an interrupt
- Edge trigger Vs. Level trigger in external interrupts
- Timer interrupt
- Interrupt priority
- Interrupt inside an interrupt
- Task switching and resource conflict
- C programming

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Polling Vs. Interrupt

- Polling
  - Ties down the CPU

```
while (true)
{
   if(PIND.2 == 0)
        //do something;
}
```

- Interrupt
  - Efficient CPU use
  - Has priority
  - Can be masked

```
main( )
{
   Do your common task
}

whenever PIND.2 is 0 then
   do something
```


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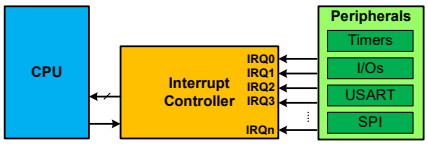
Interrupt Controllers



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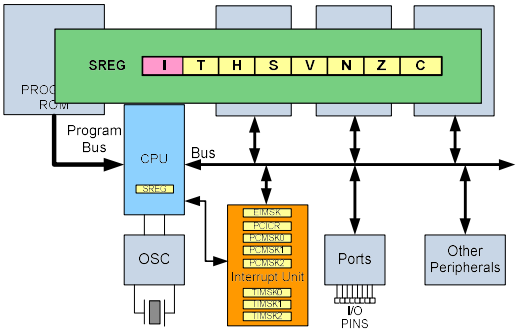
Interrupt control unit in AVR



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Interrupt vectors in ATmega328

Interrupt	Address (hex)
Reset	0000
External Interrupt Request 0	0002
External Interrupt Request 1	0004
Pin Change Interrupt Request	0006
Pin Change Interrupt Request	0008
Pin Change Interrupt Request	000A
Watchdog Time-out Interrupt	000C
Timer/Counter2 Compare Match A	000E
Timer/Counter2 Compare Match B	0010
Timer/Counter2 Overflow	0012
Timer/Counter1 Capture Event	0014
Timer/Counter1 Compare Match A	0016
Timer/Counter1 Compare Match B	0018
Timer/Counter1 Overflow	001A
Timer/Counter0 Compare Match A	001C

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External Interrupts

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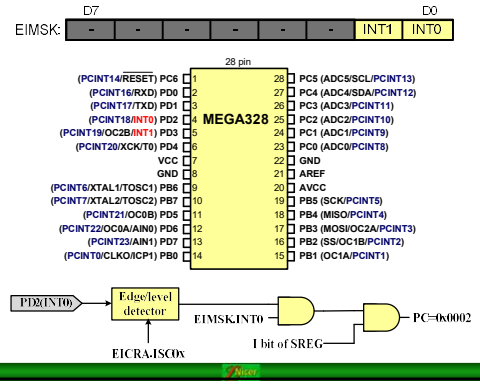
External Interrupts



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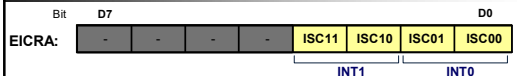
Edge trigger Vs. Level trigger in external interrupts



ISCx1	ISCx0	
0	0	
0	1	
1	0	
1	1	

```
EICRA = 0x02;  //INT0 on falling edges
```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External Interrupt Sample Code

- Write a program that whenever INT0 goes low, it toggles PB5 once.

```
1  .ORG 0 ;location for reset
2    JMP MAIN
3  .ORG 0x02 ;loc. for external INT0
4    JMP EX0_ISR
5  MAIN:
6    LDI R20,HIGH(RAMEND)
7    OUT SPH,R20
8    LDI R20,LOW(RAMEND)
9    OUT SPL,R20 ;initialize stack
10   LDI R20,0x2 ;make INT0 falling
11   STS EICRA,R20
12   SBI DDRB,5 ;PORTB.5 = output
13   SBI PORTD,2 ;pull-up activated
14   LDI R20,1<<INT0 ;enable INT0
15   OUT EIMSK,R20
16   SEI ;enable interrupts
17 HERE:JMP HERE
18 EX0_ISR:
19   IN R21,PORTB
20   LDI R22,(1<<5) ;for toggling PB5
21   EOR R21,R22
22   OUT PORTB,R21
23   RETI
24
25
```

INT0 ISR

Ex. INT0 enable

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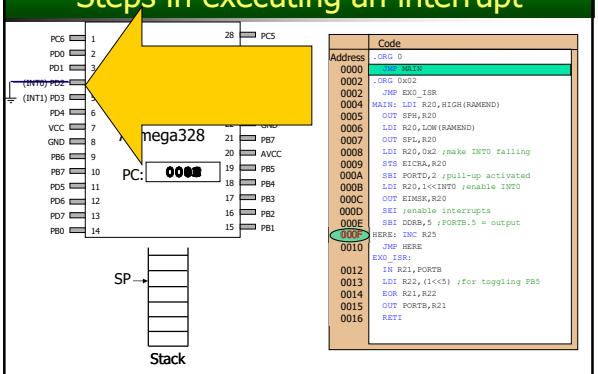
Steps in executing an interrupt



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Timer Interrupts

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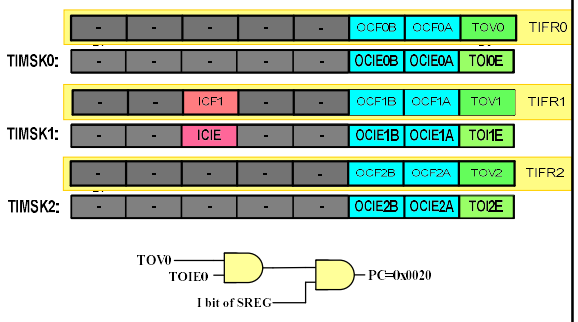
Timer Interrupts



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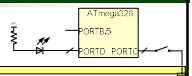
Using Timer0 overflow interrupt

- This program uses Timer0 to generate a square wave on pin PORTB.5, while at the same time data is being transferred from PORTC to PORTD.




```
1  .ORG 0x0 ;location for reset
2  JMP MAIN
3  .ORG 0x20 ;location for Timer0 ov.
4    JMP T0_OV_ISR ;jump to ISR for T0
5  ;-main program for initialization
6  MAIN: LDI R20,HIGH(RAMEND)
7    OUT SPH,R20
8    LDI R20,LOW(RAMEND)
9    OUT SPL,R20 ;initialize stack
10   LDI R20,-32 ;value for 2 us
11   OUT TCNT0,R20 ;load Timer0
12   LDI R20,0x00
13   OUT TCCR0A,R20
14   LDI R20,0x01
15   OUT TCCR0B,R20 ;Normal, no scaler
16   LDI R20,(1<<TOIE0)
17   STS TIMSK0,R20 ;enable Timer0 Ov.
18   SEI ;set I (enable Ints)
19   SBI DDRB,5 ;PB5 as an output
20   LDI R20,0x00
21   OUT DDRC,R20 ;make PORTC input
22   LDI R20,0xFF
23   OUT PORTC,R20 ;enable pull-up
24   OUT DDRD,R20 ;make PORTD output
25 HERE:IN R20,PINC ;read from PORTC
26   OUT PORTD,R20 ;give it to PORTD
27   JMP HERE
28 T0_OV_ISR:
     IN R16,PORTB ;read PORTB
     LDI R17,(1<<5) ;for toggling PB5
     EOR R16,R17
     OUT PORTB,R16 ;toggle PB5
33   LDI R16,-32 ;timer value for 2 us
     OUT TCNT0,R16;load Timer0 with -32
     RETI ;return from interrupt
```

Timer0 ISR

Timer Init

Timer Int. enable

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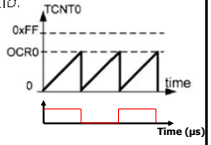
Timer0 Compare Match Interrupt

- using Timer0 and CTC mode generate a square wave on pin PORTB.5, while at the same time data is being transferred from PORTC to PORTD.

```
.ORG 0x0 ;location for reset
  JMP MAIN
.ORG 0x1C ;ISR location for Timer0 compare match A
  JMP T0_CM_ISR
;main program
MAIN:
  LDI R20,HIGH(RAMEND)
  OUT SPH,R20
  LDI R20,LOW(RAMEND)
  OUT SPL,R20;set up stack
  SBI DDRB,5;PB5 as an output
  LDI R20,239
  OUT OCR0A,R20 ;load Timer0 with 239
  LDI R20,(1<<WGM01)
  OUT TCCR0A,R20
  LDI R20,0x01
  OUT TCCR0B,R20 ;start Timer0, CTC mode, no scaler
  LDI R20,(1<<OCIE0A)
  STS TIMSK0,R20 ;enable Timer0 compare match interrupt
  SEI ;set I (enable interrupts globally)
  LDI R20,0x00
  OUT DDRC,R20 ;make PORTC input
  LDI R20,0xFF
  OUT DDRD,R20 ;make PORTD output
```




```
;--------------- Infinite loop
HERE:
  IN R20,PINC   ;read from PORTC
  OUT PORTD,R20 ;and send it to PORTD
  JMP HERE
;--ISR for Timer0 (executed every 40 µs)
T0_CM_ISR:
  IN R16,PORTB ;read PORTB
  LDI R17,1<<5 ;00100000 for toggling PB5
  EOR R16,R17
  OUT PORTB,R16 ;toggle PB5
  RETI ;return from interrupt
```

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Pin Change Interrupts

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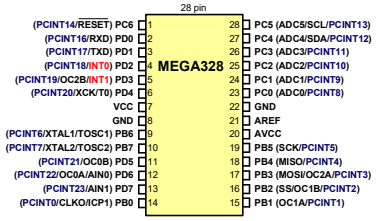
Pin Change Mask Registers

	Bit	D7							D0	
PCMSK0: (for PORTB)		PCINT7	PCINT6	PCINT5	PCINT4	PCINT3	PCINT2	PCINT1	PCINT0	0x6B
PCMSK1: (for PORTC)		PCINT15	PCINT14	PCINT13	PCINT12	PCINT11	PCINT10	PCINT9	PCINT8	0x6C
PCMSK2: (for PORTD)		PCINT23	PCINT22	PCINT21	PCINT20	PCINT19	PCINT18	PCINT17	PCINT16	0x6D



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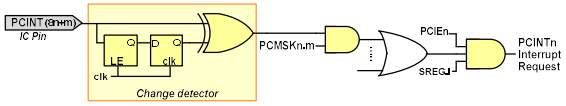
Pin Change Interrupt



	Bit	D7							D0	
PCICR:		-	-	-	-	-	-	PCIE2	PCIE1	PCIE0	0x68

PCIE0: Pin Change Interrupt Enable bit for PORTB
PCIE1: Pin Change Interrupt Enable bit for PORTC (0: disabled, 1: enabled)
PCIE2: Pin Change Interrupt Enable bit for PORTD (0: disabled, 1: enabled)

	Bit	D7							D0	
PCMSK0: (for PORTB)		PCINT7	PCINT6	PCINT5	PCINT4	PCINT3	PCINT2	PCINT1	PCINT0	0x6B
PCMSK1: (for PORTC)		PCINT15	PCINT14	PCINT13	PCINT12	PCINT11	PCINT10	PCINT9	PCINT8	0x6C
PCMSK2: (for PORTD)		PCINT23	PCINT22	PCINT21	PCINT20	PCINT19	PCINT18	PCINT17	PCINT16	0x6D

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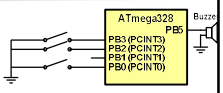
Pin Change Int. Sample Code

- The PB0, PB2, and PB3 pins are connected to switches. Write a program that makes PORTB.5 high whenever any of the switches changes state.




```
1  .ORG 0  ;location for reset
2          JMP     MAIN
3  .ORG 0x06 ;loc. for PCINT0
4          JMP     PCINT0_ISR
5  MAIN:   LDI     R20,HIGH(RAMEND)
6          OUT     SPH,R20
7          LDI     R20,LOW(RAMEND)
8          OUT     SPL,R20
9          SBI     DDRB,5
10         CBI     PORTB,5
11  ;enable pull-up resistors
12         OUT     PORTB,R20
13 ;enable PB0, PB2, and PB3 PCINTs
14         LDI     R20,0b00001101
15         STS     PCMSK0,R20
16 ;enable PORTB change interrupt
17         LDI     R20,(1<<PCIE0)
18         STS     PCICR,R20
19         SEI
20 HERE:   JMP     HERE
21
22 PCINT0_ISR:
23         SBI     PORTB,5
24         RETI
25
26
27
28
29
30
```

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Interrupt priority

Interrupt	Address (hex)
Reset	0000
External Interrupt Request 0	0002
External Interrupt Request 1	0004
Pin Change Interrupt Request	0006
Pin Change Interrupt Request	0008
Pin Change Interrupt Request	000A
Watchdog Time-out Interrupt	000C
Timer/Counter2 Compare Match A	000E
Timer/Counter2 Compare Match B	0010
Timer/Counter2 Overflow	0012
Timer/Counter1 Capture Event	0014
Timer/Counter1 Compare Match A	0016
Timer/Counter1 Compare Match B	0018
Timer/Counter1 Overflow	001A
Timer/Counter0 Compare Match A	001C
Timer/Counter0 Compare Match B	001E
Timer/Counter0 Overflow	0020
SPI Serial Transfer Complete	0022
USART Rx Complete	0024
USART Data Register Empty	0026
USART Tx Complete	0028
ADC Conversion Complete	002A
EEPROM ready	002C
Analog Comparator	002E

Highest priority

Lowest priority

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Interrupt inside an interrupt

- The I flag is cleared when the AVR begins to execute an ISR. So, interrupts are disabled.
- The I flag is set when RETI is executed.

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Task switching and resource conflict

- Does the following program work?

```
1  .ORG    0x0       ;location for reset
2          JMP       MAIN
3  .ORG    0x1C      ;Timer0 compare match
4          JMP       T0_CM_ISR
5  ;---------main program-----------------------------
6  MAIN:   LDI       R20,HIGH(RAMEND)
7          OUT       SPH,R20
8          LDI       R20,LOW(RAMEND)
9          OUT       SPL,R20  ;set up stack
10         LDI       R20,159
11         OUT       OCR0A,R20
12         LDI       R20,(1<<WGM01)
13         OUT       TCCR0A,R20
14         LDI       R20,0x01
15         OUT       TCCR0B,R20
16         LDI       R20,(1<<OCIE0A)
17         STS       TIMSK0,R20
18         SEI
19         LDI       R20,0xFF
20         OUT       DDRC,R20
21         OUT       DDRD,R20
22 HERE:   OUT       PORTC,R20
23         INC       R20
24         JMP       HERE
25 ;-------------------------ISR for Timer0
26 T0_CM_ISR:
27         IN        R20,PIND
28         INC       R20
29         OUT       PORTD,R20
30         RETI
```


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Solution 1: different registers

- Use different registers for different tasks.

```
1  .ORG    0x0       ;location for reset
2          JMP       MAIN
3  .ORG    0x1C      ;Timer0 compare match
4          JMP       T0_CM_ISR
5  ;---------main program-----------------------------
6  MAIN:   LDI       R20,HIGH(RAMEND)
7          OUT       SPH,R20
8          LDI       R20,LOW(RAMEND)
9          OUT       SPL,R20  ;set up stack
10         LDI       R20,159
11         OUT       OCR0A,R20
12         LDI       R20,(1<<WGM01)
13         OUT       TCCR0A,R20
14         LDI       R20,0x01
15         OUT       TCCR0B,R20
16         LDI       R20,(1<<OCIE0A)
17         STS       TIMSK0,R20
18         SEI
19         LDI       R20,0xFF
20         OUT       DDRC,R20
21         OUT       DDRD,R20
22
23         LDI       R20, 0
24 HERE:   OUT       PORTC,R20
25         INC       R20
26         JMP       HERE
27 ;-------------------------ISR for Timer0
28 T0_CM_ISR:
29         IN        R21,PIND
30         INC       R21
31         OUT       PORTD,R21
32         RETI
```


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Solution 2: Context saving

- Save the contents of registers on the stack before execution of each task, and reload the registers at the end of the task.

```
1  .ORG    0x0       ;location for reset
2          JMP       MAIN
3  .ORG    0x1C      ;Timer0 compare match
4          JMP       T0_CM_ISR
5  ;---------main program-----------------------------
6  MAIN:   LDI       R20,HIGH(RAMEND)
7          OUT       SPH,R20
8          LDI       R20,LOW(RAMEND)
9          OUT       SPL,R20  ;set up stack
10         LDI       R20,159
11         OUT       OCR0A,R20
12         LDI       R20,(1<<WGM01)
13         OUT       TCCR0A,R20
14         LDI       R20,0x01
15         OUT       TCCR0B,R20
16         LDI       R20,(1<<OCIE0A)
17         STS       TIMSK0,R20
18         SEI
19         LDI       R20,0xFF
20         OUT       DDRC,R20
21         OUT       DDRD,R20
22         LDI       R20, 0
23 HERE:   OUT       PORTC,R20
24         INC       R20
25         JMP       HERE
26 ;-------------------------ISR for Timer0
27 T0_CM_ISR:
28         PUSH      R20      ;save R20
29         IN        R20,PIND
30         INC       R20
31         OUT       PORTD,R20
32         POP       R20      ;restore R20
33         RETI
34
```


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Solution 3: Context saving using software stack

- Make a stack for yourself and use it to save the contents of registers.

```
1  .ORG    0x0          ;location for reset
2          JMP     MAIN
3  .ORG    0x1C         ;Timer0 compare match
4          JMP     T0_CM_ISR
5  ;---------main program-----------------------------
6  MAIN:   LDI     R20,HIGH(RAMEND)
7          OUT     SPH,R20
8          LDI     R20,LOW(RAMEND)
9          OUT     SPL,R20  ;set up stack
10         LDI     YH, HIGH($100)
11         LDI     YL, LOW($100)
12
13         LDI     R20,159
14         OUT     OCR0A,R20
15         LDI     R20,(1<<WGM01)
16         OUT     TCCR0A,R20
17         LDI     R20,0x01
18         OUT     TCCR0B,R20
19         LDI     R20,(1<<OCIE0A)
20         STS     TIMSK0,R20
21         SEI
22         LDI     R20,0xFF
23         OUT     DDRC,R20
24         OUT     DDRD,R20
25         LDI     R20, 0
26 HERE:   OUT     PORTC,R20
27         INC     R20
28         JMP     HERE
29 ;-------------------------ISR for Timer0
30 T0_CM_ISR:
31         ST      Y+,R20   ;save R20
32         IN      R20,PIND
33         INC     R20
34         OUT     PORTD,R20
35         LD      R20, -Y  ;restore R20
36         RETI
```


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Saving SREG

- We should save SREG, when we change flags in the ISR.

```
PUSH    R20
IN      R20,SREG
PUSH    R20
...
POP     R20
OUT     SREG,R20
POP     R20
```


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C programming

- Using Timer0 generate a sq
  same time transferring data

```
#include "avr/io.h"
#include "avr/interrupt.h"
int main ()
{
    DDRB |= (1<<5);     //DDRB
    TCNT0 = -32;        //time
    TCCR0A = 0x00;
    TCCR0B = 0x01;
    TIMSK0 = (1<<TOIE0);
    sei ();
    DDRC = 0x00;
    DDRD = 0xFF;
    while (1)           //wait
        PORTD = PINC;
}
ISR (TIMER0_OVF_vect) //ISR
{
    TCNT0 = -32;
    PORTB ^= 0x20;      //togg
}
```

Interrupt	Vector Name
External Interrupt Request 0	INT0_vect
External Interrupt Request 1	INT1_vect
Pin Change Interrupt Request	PCINT0_vect
Pin Change Interrupt Request	PCINT1_vect
Pin Change Interrupt Request	PCINT2_vect
Watchdog Time-out Interrupt	WDT_vect
Timer/Counter2 Compare Match A	TIMER2_COMPA_vect
Timer/Counter2 Compare Match B	TIMER2_COMPB_vect
Timer/Counter2 Overflow	TIMER2_OVF_vect
Timer/Counter1 Capture Event	TIMER1_CAPT_vect
Timer/Counter1 Compare Match A	TIMER1_COMPA_vect
Timer/Counter1 Compare Match B	TIMER1_COMPB_vect
Timer/Counter1 Overflow	TIMER1_OVF_vect
Timer/Counter0 Compare Match A	TIMER0_COMPA_vect
Timer/Counter0 Compare Match B	TIMER0_COMPB_vect
Timer/Counter0 Overflow	TIMER0_OVF_vect
SPI Serial Transfer Complete	SPI_STC_vect
USART Rx Complete	USART_RX_vect
USART Data Register Empty	USART_UDRE_vect
USART Tx Complete	USART_TX_vect

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C programming Example 2

- Using Timer1 and CTC mode write a program that toggles pin PORTB.5 every second, while at the same time transferring data from PORTC to PORTD. Assume XTAL = 16 MHz.

```
#include <avr/io.h>
#include <avr/interrupt.h>
int main () {
        DDRB |= (1<<5);         //make DDRB.5 output

        OCR1A = 15624;
        TCCR1A = 0x00; //CTC mode, internal clk, prescaler=1024
        TCCR1B = 0x0D;
        TIMSK1 = (1<<OCIE1A); //enable Timer1 compare match A int.
        sei ();               //enable interrupts

        DDRC = 0x00;          //make PORTC input
        DDRD = 0xFF;          //make PORTD output
        while (1)             //wait here
                PORTD = PINC;
}
ISR (TIMER1_COMPA_vect) {     //ISR for Timer1 compare match A
        PORTB ^= (1<<5);      //toggle PORTB.5
}
```

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C programming Example 3

- Assume that the INT0 pin is connected to a switch that is normally high. Write a program that toggles PORTB.5, whenever INT0 pin goes low.

```
#include <avr/io.h>
#include <avr/interrupt.h>
int main ()
{
        DDRB = 1<<5;          //PB5 as an output
        PORTD = 1<<2;         //pull-up activated
        EICRA = 0x2;          //make INT0 falling edge triggered

        EIMSK = (1<<INT0);    //enable external interrupt 0
        sei ();               //enable interrupts

        while (1);                      //wait here
}

ISR (INT0_vect)                         //ISR for external interrupt 0
{
        PORTB ^= (1<<5);                //toggle PORTB.5
}
```

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