TECH 3233 Lab #4b Ver 1.5

Lab #4a we used LED's for the output, now we are going to replace the LED's with a Stepper Motor and Driver.

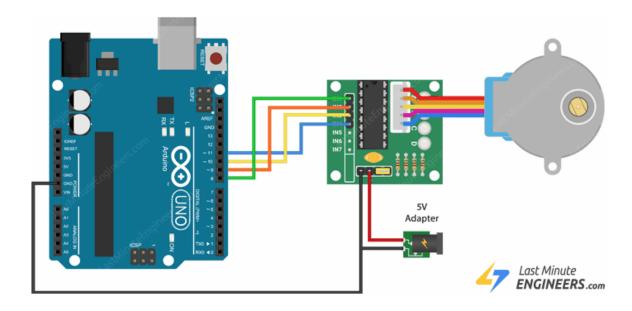


Figure 1- Wiring¹

- Connect IN1, IN2, IN3 and IN4 to PB0, PB1, PB2 and PB3 respectively.
- Connect the 9v battery connector (Red to + and Black to -)
- Connect the MALE black wire from the 9v battery to the Arduino GND pin (Shown above as the 5v Adapter)
- Lastly connect the stepper motor to the white connector on the board.

You will need to decrease your timers from 300ms to around 10ms to get a reasonable motor movement.

¹ https://lastminuteengineers.com/28byj48-stepper-motor-arduino-tutorial/

Now for the next part of the lab we will be working off our Lab #4a, we are now going to add 3 input switches and add the following functionality:

Pin	Function	Description	
PD2	Run/ Stop	When on (unbarred) the stepper motor	
		will run. When off (Barred) the motor	
		will stop.	
PD3	Fwd/\overline{Rev}	When on, the motor will run in the	
		clockwise direction (looking at the	
		shaft). When off, the motor will run	
		counter clockwise.	
PD4	Full/ Half	When on the motor will run in full step	
		mode, when off the motor will run in	
		half step mode.	

Please use the internal pull up's for this experiment.

Half step pattern is:

PB3	PB2	PB1	PB0
		\bigcirc	
		\bigcirc	

Also, you are required to use the PIN NAME with _BV method for this (and all upcoming assignments) where appropriate.

Please demo the working program and submit your fully commented code via the assignment submission system.